

Milestone Review Flysheet

Institution University of South Florida

Milestone Critical Design Review

| Vehicle Properties | |
|---------------------------|----------------|
| Total Length (in) | 138 |
| Diameter (in) | 4 |
| Gross Lift Off Weigh (lb) | 23.2 |
| Airframe Material | G12 Fiberglass |
| Fin Material | G10 Fiberglass |
| Drag | 62 lbf |

| Motor Properties | |
|-------------------------|-----------------|
| Motor Manufacturer | Cesaroni |
| Motor Designation | CS L910s |
| Max/Average Thrust (lb) | 244.165/203.924 |
| Total Impulse (lbf-s) | 1919.21 |
| Mass Before/After Burn | 23.2/17.1 lb |
| Liftoff Thrust (lb) | 235 |

| Stability Analysis | |
|---|-----------|
| Center of Pressure (in from nose) | 114 in |
| Center of Gravity (in from nose) | 92.512 in |
| Static Stability Margin | 5.38 |
| Static Stability Margin (off launch rail) | 5.38 |
| Thrust-to-Weight Ratio | 8.93 |
| Rail Size and Length (in) | 121 |
| Rail Exit Velocity | 82.3 ft/s |

| Ascent Analysis | |
|----------------------------------|------|
| Maximum Velocity (ft/s) | 746 |
| Maximum Mach Number | 0.67 |
| Maximum Acceleration (ft/s^2) | 298 |
| Target Apogee (From Simulations) | 5280 |
| Stable Velocity (ft/s) | 85 |
| Distance to Stable Velocity (ft) | 11 |

| Recovery System Properties | | | | |
|---|-----------|---|-----------|-----------|
| Dogue Parachute | | | | |
| Manufacturer/Model | | SkyAngle | | |
| Size | | 6.3 sq ft | | |
| Altitude at Deployment (ft) | | Apogee | | |
| Velocity at Deployment (ft/s) | | 0 | | |
| Terminal Velocity (ft/s) | | 63.04 | | |
| Recovery Harness Material | | Tubular Nylon | | |
| Harness Size/Thickness (in) | | 1 | | |
| Recovery Harness Length (ft) | | 34.5 | | |
| Harness/Airframe Interfaces | | Connection between eye bolts on the Nosecone/Payload Bay Bulkhead and Fore Altimeter Bay fastened to the Fore airframe. | | |
| Kinetic Enerfy of Each Section (Ft-lbs) | Section 1 | Section 2 | Section 3 | Section 4 |
| | 190.8 | 219.745 | 448.067 | |

| Recovery System Properties | | | | |
|---|-----------|--|-----------|-----------|
| Main Parachute | | | | |
| Manufacturer/Model | | SkyAngle | | |
| Size | | 56 sq. ft | | |
| Altitude at Deployment (ft) | | 500 | | |
| Velocity at Deployment (ft/s) | | 63.04 | | |
| Terminal Velocity (ft/s) | | 15.93 | | |
| Recovery Harness Material | | Tubular Nylon | | |
| Harness Size/Thickness (in) | | 1 | | |
| Recovery Harness Length (ft) | | 34.5 | | |
| Harness/Airframe Interfaces | | Connection between eye bolts on Aft altimeter Bay and eye bolts on top centering ring of the motor mount | | |
| Kinetic Enerfy of Each Section (Ft-lbs) | Section 1 | Section 2 | Section 3 | Section 4 |
| | 12.184 | 14.032 | 26.612 | |

| Recovery Electronics | |
|--------------------------------------|--|
| Altimeter(s)/Timer(s) (Make/Model) | RRC3/Missile Works |
| Redundancy Plan | 2 Altimeters wired to redundant seperation charges |
| Pad Stay Time (Launch Configuration) | 3 Hours |

| Recovery Electronics | |
|--|-------------------------------------|
| Rocket Locators (Make/Model) | TeleGPS/Apogee |
| Transmitting Frequencies | 100kHz Band starting at 434.550 MHz |
| Black Powder Mass Drogue Chute (grams) | 3.5 g |
| Black Powder Mass Main Chute (grams) | 4 g |

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Autonomous Ground Support Equipment (MAV Teams Only)

| | |
|--------------------------------|--|
| | Overview |
| Capture Mechanism | The robotic arm will be attached to the base of a rover mechanism. After the payload has been approached a camera on the end of the robotic gripper will determine the payload location and orient itself for capture. Upon capture the rover will return to a predefined base and confirm payload location and orientation at a static camera attached to the base of the rail. |
| | Overview |
| Container Mechanism | The container mechanism for the AGSE is a linear actuator system, with an attached payload sled that can be closed or opened with radio signalling. |
| | Overview |
| Launch Rail Mechanism | The launch rail will be lifted by a worm and gear mechanism. A locking rod will move from groove to groove in order to safely support the rod from slippage. The ratcheting mechanism will also serve to increment the number of degrees raised using discrete units that will allow us to definitively raise the rail to 15 degrees from vertical. |
| | Overview |
| Igniter Installation Mechanism | The igniter will be installed in a linear actuator attached to the baseplate of the AGSE rail. The igniter will be kept straight by a guide hole in the blast plate and directed upwards by the linear actuator after the launch rail is in position. |

Payload

| | |
|-----------|---|
| | Overview |
| Payload 1 | The AGSE payload will be a sealed PVC pipe 3" in length and 3/4" in diameter filled with sand in order to weigh 4 oz. |
| | Overview |
| Payload 2 | |

Test Plans, Status, and Results

| | |
|-------------------------|---|
| Ejection Charge Tests | The ejection charge tests precede each launch with programming of altimeter and test fires. |
| Sub-scale Test Flights | The subscale launch was a success with an achieved altitude of 4092 feet. |
| Full-scale Test Flights | The full-scale test launch is scheduled for 2/20/16 |

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Additional Comments